

(12) INTERNATIONAL APPLICATION PUBLISHED UNDER THE PATENT COOPERATION TREATY (PCT)

(19) World Intellectual Property Organization
International Bureau



(43) International Publication Date
28 August 2003 (28.08.2003)

PCT

(10) International Publication Number
WO 03/071150 A1

(51) International Patent Classification⁷: F16D 55/22, B60T 13/72

(21) International Application Number: PCT/SE03/00290

(22) International Filing Date: 21 February 2003 (21.02.2003)

(25) Filing Language: English

(26) Publication Language: English

(30) Priority Data:
0200495-0 21 February 2002 (21.02.2002) SE
60/359,729 27 February 2002 (27.02.2002) US

(71) Applicant (for all designated States except US): HALDEX
BRAKE PRODUCTS AB [SE/SE]; Box 501, S-261 24
Landskrona (SE).

(81) Designated States (national): AE, AG, AL, AM, AT, AU, AZ, BA, BB, BG, BR, BY, BZ, CA, CH, CN, CO, CR, CU, CZ, DE, DK, DM, DZ, EC, EE, ES, FI, GB, GD, GE, GH, GM, HR, HU, ID, IL, IN, IS, JP, KE, KG, KP, KR, KZ, LC, LK, LR, LS, LT, LU, LV, MA, MD, MG, MK, MN, MW, MX, MZ, NO, NZ, OM, PH, PL, PT, RO, RU, SD, SE, SG, SK, SL, TJ, TM, TN, TR, TT, TZ, UA, UG, US, UZ, VN, YU, ZA, ZM, ZW.

(84) Designated States (regional): ARIPO patent (GH, GM, KE, LS, MW, MZ, SD, SL, SZ, TZ, UG, ZM, ZW), Eurasian patent (AM, AZ, BY, KG, KZ, MD, RU, TJ, TM), European patent (AT, BE, BG, CH, CY, CZ, DE, DK, EE, ES, FI, FR, GB, GR, HU, IE, IT, LU, MC, NL, PT, SE, SI, SK, TR), OAPI patent (BF, BJ, CF, CG, CI, CM, GA, GN, GQ, GW, ML, MR, NE, SN, TD, TG).

Published:

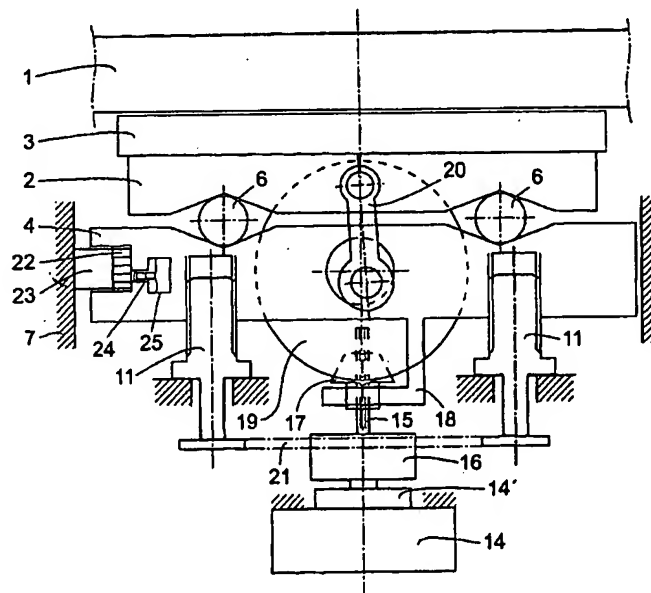
— with international search report

For two-letter codes and other abbreviations, refer to the "Guidance Notes on Codes and Abbreviations" appearing at the beginning of each regular issue of the PCT Gazette.

(72) Inventor; and
(75) Inventor/Applicant (for US only): SEVERINSSON,
Lars [SE/SE]; Nordanåvägen 27, S-310 21 Hishult (SE).

(74) Agent: STRÖM & GULLIKSSON IPC AB; P.O. Box
4188, S-203 13 Malmö (SE).

(54) Title: A DISC BRAKE



(57) Abstract: An electronically controlled disc brake with self-servo effect comprises a ramp plate (2) provided with a brake pad (3) for engagement with a brake disc (1), an actuator (14) for applying a control force on the ramp plate substantially transverse to the brake disc, a ramp bridge (4), and rollers (6) movable in ramps (2', 4') in surfaces facing each other of the ramp plate (2) and the ramp bridge (4). The arrangement of these members is such that a movement of the ramp plate (2) in the tangential direction of the brake disc (1) will cause it to move towards or away from the brake disc.



WO 03/071150 A1

A DISC BRAKE

Technical Field

5 The present invention relates to an electronically controlled disc brake with self-servo effect.

Background of the Invention

It is well known in the art that a self-servo effect for a disc brake on a vehicle may be obtained by applying a
10 brake pad against the rotating brake disc, where the brake pad is tangentially movable in relation to the brake disc over inclined ramp means or the like.

The problem with such designs has hitherto been the relatively poor controllability, especially if hydraulic or
15 pneumatic brake actuators have been used and if a great self-servo effect was desired.

We now see an increasing use of electronically controlled brake actuators, especially electric motors, which greatly improve the controllability of the brakes.

20 The main object of the invention is to accomplish a disc brake of this kind, which is as simple, cheap and effective as possible, providing a low level of actuation energy, low weight and high reliability, and which may provide the desired self-servo effect in both rotation
25 directions of the brake disc, which is of importance not only for service braking but also for parking braking.

The Invention

This may according to the invention be obtained in that a disc brake comprises

30 a ramp plate provided with a brake pad for engagement with a brake disc,

an actuator for applying a control force on the ramp plate substantially transverse to the brake disc,

a ramp bridge, and

35 rollers movable in ramps in surfaces facing each other of the ramp plate and the ramp bridge,

the arrangement being such that a movement of the ramp plate in the tangential direction of the brake disc will cause it to move towards or away from the brake disc.

For enabling the ramp plate to obtain a position
5 substantially parallel with the brake disc at all times, there are preferably two ramp and roller arrangements between the ramp plate and the ramp bridge, but in certain cases the number of such arrangements may be higher.

The ramp bridge is normally attached to a brake
10 caliper placed astraddle of the brake disc.

The ramps may be straight or curved depending on the desired characteristics of the disc brake.

The movement of the rollers may be synchronized by means of a common roller cage, especially if the ramps are
15 curved.

It has been stated that the actuator may be pneumatic or hydraulic, but it is preferred to use an electric motor as the actuator.

The control force may as a first alternative be
20 applied by means of a control rod.

However, as a second and presently preferred alternative, the control force is applied over an eccentric mechanism between the ramp plate and the ramp bridge, the eccentricity of the mechanism and thus the distance between
25 the ramp plate and the ramp bridge being adjustable by means of the electric motor.

In the force transmission from the electric motor there is preferably provided a brake means for keeping the outgoing shaft of the motor non-rotatable, when the motor
30 is not energized for rotation in either of its two rotational directions.

In a practical embodiment the rotation of the electric motor is transferred to the eccentric mechanism via an angle transmission from a motor rod to a bevel gear

disc, which is rotatably attached to the ramp bridge and is part of the eccenter mechanism.

Preferably the rotation of the electric motor is transferred to the eccenter mechanism via a bevel gear on the motor rod in engagement with the bevel gear disc, but
5 alternatively a worm gear mechanism may be used instead of the bevel gear and the bevel gear disc.

As the ramp bridge may be movable in relation to the fixed motor, the bevel gear is axially movable on the motor
10 rod by being in splines engagement therewith.

In order to obtain a brake clearance adjusting function of the disc brake, thus compensating for the wear of the brake pad at braking, the position of the ramp bridge in relation to the brake caliper may be adjusted in
15 the direction transverse to the brake disc by means of two adjustment screws.

The two adjustment screws are preferably connected by means of a chain or the like for their synchronous rotation.

20 In order to provide - to a control system for the disc brake - a signal corresponding to the obtained tangential brake force, a force sensing means can be arranged between the ramp bridge and the brake caliper.

If a force sensing means is arranged at either side
25 of the ramp bridge, signals are provided in both rotation directions and the disc brake may also be mounted in optional positions.

There may further be force sensing means between the adjustment screws and the caliper for providing a signal
30 indicative of the axial brake force.

In a first preferred embodiment of an eccenter mechanism a crank rod is pivotably attached at one of its ends to the ramp plate and at its other end eccentrically to the bevel gear.

In a second embodiment of an eccentric mechanism a roller is eccentrically rotatably attached to the bevel gear and is in engagement with a slot in the ramp plate substantially parallel with the brake disc.

5

Brief Description of the Drawings

The invention will be described in further detail below under reference to the accompanying drawings, in which

10

Fig 1 is a very schematic top view of a disc brake arrangement for illustrating a principle of the invention,

Figs 2 and 3 are schematic top views of disc brake calipers embodying the invention, and

Figs 4-6 are schematic top views of embodiments of a disc brake according to the invention.

15

Description of Embodiments

As shown in Fig 1, a brake disc 1 is rotating in the direction of an arrow 1'. A ramp plate 2 is provided with a brake pad 3 for braking engagement with the brake disc 1 at will. The ramp plate 2 is movably connected to a ramp bridge 4, which for the purpose of this simple explanation can be regarded as fixed, by a connecting means 5, here illustrated as a line.

20

At their surfaces facing each other, the ramp plate 2 and the ramp bridge 4 are provided with curved or straight ramps 2' and 4', respectively. A roller 6 is freely rotatable between the ramps 2' and 4'.

25

In a rest position (or a position for a non-applied brake) the unit comprising the ramp plate 2 (with its brake pad 3), the roller 6 and the ramp bridge 4 is held with the brake pad 3 at a small distance from the rotating brake disc 1 and with the roller 6 in the "bottoms" of the ramps 2' and 4'.

30

For brake application, a control force which is substantially transverse to the brake disc 1 (or in other words substantially axial) is applied on the ramp plate 2,

35

in the shown case over the connecting means 5 as indicated by its upper arrow, until contact between the brake pad 3 and the disc 1 is established. By means of the friction force, the ramp plate 2 is transferred to the left in the drawing, so that the roller 6 rolls up the relevant ramps 2' and 4' and an application force is accomplished without applying any external brake force besides the control force. In other words the brake has a self-servo effect.

The application force may be controlled by the control force, which can be positive or negative. This is indicated by the provision of also a lower arrow on the connecting means 5, but is not further illustrated and described in connection with Fig 1.

If the brake disc 1 rotates in the opposite direction, the arrangement will function in a similar way due to the provision of the respective double ramps 2' and 4'.

In the shown case the ramps 2' and 4' are curved, but they can alternatively be straight. By having a certain curvature of the ramps, a desired brake application characteristic can be obtained.

In Fig 2 there is schematically shown a disc brake caliper 7 to be placed astraddle of a brake disc (not shown). The caliper 7 is provided with a fixed brake pad 8 at the side of the brake disc opposite the brake pad 3 of the ramp plate 2. Rollers 6 are arranged between double-sided ramps 2' on the ramp plate 2 and corresponding ramps 7' on the caliper 7. An axial control force can be applied to the ramp plate 2 by means of a control rod 9 acting on the ramp plate 2 via a roller or ball 10 for enabling the ramp plate 2 to move perpendicular thereto or tangentially with the brake disc (not shown).

In the same manner as has been described above, the ramp plate 2 will be transferred by friction forces between the brake disc (not shown) and the brake pad 3, and a brake

application with self-servo effect will be accomplished by the rollers 6 rolling up the ramps 2' and 7'.

The provision of two rollers 6 is necessary in order to support the ramp plate 2 with its brake pad 3
5 substantially parallel with the brake disc.

In this arrangement the control force is applied by the control rod 9. By proper choice of ramp angles for non-self-locking of the brake pad 3 to the brake disc 1, the application force can be controlled by a control force that
10 is always positive.

Fig 3 shows a brake arrangement of substantially the same kind as that shown in Fig 2 but with more features and a higher degree of sophistication.

Again, a disc brake caliper 7 is to be placed
15 astraddle of a brake disc (not shown). The caliper 7 is provided with a brake pad 8. The ramp plate 2 is provided with a brake pad 3 on the opposite side of the brake disc. A ramp bridge 4 is supported by the caliper 7 by means of two adjustment screws 11. Two rollers 6 are arranged
20 between ramps 2' and 4' in the ramp plate 2 and the ramp bridge 4, respectively.

A control rod 9 is axially movably guided in the ramp bridge 4 and applies a control force over a rod plate 9' acting on balls or rollers 10.

25 A negative control force on the ramp plate 2 can also be accomplished in that the ramp plate 2 is provided with a cage 2', on which return rollers 12 in contact with the rod plate 9' can act at a negative control force on the control rod 9. In practice the control rod may be rotated by an
30 electric motor (not shown), and its axial movement may be accomplished by a ball screw arrangement 13 between the ramp bridge 4 and the control rod 9.

The purpose of the adjustments screws 11 is to properly position the ramp plate/bridge unit with the brake

pad 3 at a small distance from the brake disc (not shown), ready for brake application.

The arrangement according to Fig 3 will be fully controllable for instant applications and releases by the electric motor rotating the control rod 9, and the
5 controllable self-servo effect is obtained in both rotation directions of the brake disc placed between the two brake pads 3 and 8.

A disc brake arrangement shown in Fig 4 has
10 functional similarities with the one shown in Fig 3. In this Figure the caliper is only indicated as attachment or support portions, whereas on the other hand the brake disc 1 is shown, with which the brake pad 3 on the ramp plate 2 is to cooperate.

15 The ramp bridge 4 is connected to the indicated caliper by means of two adjustment screws 11 in two threaded bores in the ramp bridge 4. Two rollers 6 are arranged between ramps 2' and 4' on the ramp plate 2 and the ramp bridge 4, respectively.

20 Although it is not shown in Fig 4 or any other Figure, it may be advantageous for obtaining full control and a completely synchronous movement of the rollers 6 (irrespective of their actual number) to provide a common roller cage for the rollers 6, especially for curved ramps
25 2' and 4'.

The mechanism for creating the control force is different from that of Fig 3.

An electric motor 14 can rotate a motor rod 15 in either direction over a rotational speed reducing gear box
30 16. A bevel gear 17 supported by an arm 18 from the ramp bridge 4 can be rotated by the rod 15 but is axially movable thereon by a splines engagement. The bevel gear 17 is in driving gear engagement with a bevel gear disc 19 rotationally supported by the ramp bridge 4. Eccentrically

connected to the bevel gear disc 19 is a crank rod 20 rotationally connected to the ramp plate 2.

By turning the bevel gear disc 19 in either direction by means of the bevel gear 17 from the motor 14 over the gear box 16, the position of the ramp plate 2 in relation to the ramp bridge 4 can be set. In this case the control force is transmitted by the crank rod 20. When a friction engagement between the brake pad 3 and the brake disc 1 has been established an application force amplification will be accomplished by the rollers 6 climbing its ramps 2' and 4' in response to the tangential movement of the ramp plate 2 caused by the friction engagement with the brake disc 1. The application force may be accurately controlled by rotating the motor 14 in either direction.

The adjustment screws 11 have the purpose of adjusting the position of the ramp bridge 4 in relation to the wear of the brake pad 3 (and the corresponding brake pad on the opposite side of the brake disc 1). The synchronous rotation of the adjustment screws 11 is performed from the gear box 16 by a chain 21 in a way not further described.

In the force transmission from the motor 14 there may be provided an active or passive brake means 14' for the purpose of preventing the motor 14 from consuming current, when there is no command from the driver of the vehicle or the control system of the brake to rotate the motor in any direction. The brake means 14' accordingly has the function to keep the outgoing motor shaft non-rotatable, when the motor 14 is not energized to rotate in either of its two rotational directions.

In a disc brake with self-servo effect of the kind described herein it is of great importance to incorporate a control system for governing the rotation of the motor 14 for obtaining the desired brake function. An important parameter for this control function is the actual

tangential brake force obtained. In the present case this parameter may be assessed in the following way.

A force sensing means of any suitable kind is arranged between the only indicated caliper 7 and the ramp
5 bridge 4. Such a force sensing means can transmit signals indicative of the tangential brake force.

For example, a pressure-transmitting medium 22, preferably rubber, is arranged in a bore in the transverse end of the ramp bridge 4 and is acted on by a plunger 23 in
10 contact with the caliper. A push rod 24 is in contact with the medium 22 at one of its ends and with a sensor element 25 at its other end. Signals indicative for the force applied by the push rod 24 and thus the pressure in the medium 22 can be transmitted from the sensor element 25 to
15 the control system of the brake.

A similar force sensing means may also be arranged at the other end of the ramp bridge 4 for providing force signals at a rotation in the opposite direction of the brake disc 1 or in other words at reverse driving of the
20 vehicle on which the brake arrangement is mounted. A further advantage with this is that the disc brake may be mounted at the left or right hand side of the vehicle.

Further, similar force sensing means (not shown) may be arranged between the caliper 7 and the adjustment screws
25 11 for obtaining signals indicative of the forces transverse to the brake disc 1 or in other words the axial forces to be supplied to the control system of the brake.

Fig 5 shows a slightly amended version of the brake shown in Fig 4. For the sake of clarity, reference numerals
30 are only provided for parts that differ between the versions of Figs 4 and 5. (In Fig 5 - as well as in Fig 6 to be described below - the motor brake means 14' and the gear box 16 are omitted.)

In the version according to Fig 5 the adjustment
35 screws 11 are non-rotatably attached to the caliper,

whereas the ramp bridge 4 is provided with rotatable nuts 26 connected by a chain 21 for synchronous movement of the ramp bridge 4 at the two adjustment screws 11.

A further embodiment of Fig 6 has many similarities with that of Fig 4, and again only parts that differ between the two embodiments are described and provided with reference numerals.

In this embodiment there is no crank rod 20 from the bevel gear disc 19 on the ramp bridge 4 for eccentrically controlling the distance between the ramp plate 2 and the ramp bridge 4. Instead there is an eccentrically positioned roller 27 on the bevel gear disc 19 for cooperation with a slot 28 in a portion of the ramp plate 2 extending past the eccentric roller 27, said slot being substantially parallel with the brake disc 1 and having a width corresponding to the diameter of the roller 27. At a turning of the bevel gear disc 19 and a corresponding movement of the eccentric roller 27 in the slot 28 the mutual distance between the ramp plate 2 and the ramp bridge 4 will be changed.

For obtaining specific characteristics of the brake the slot 28 may alternatively be given a certain curve shape.

It is obvious that many modifications and improvements may be made within the scope of the amended claims. For example, in the embodiments according to Figs 2-6 the number of ramp and roller arrangements 2', 4', 6 is two in order to ensure that the ramp plate 2 is kept parallel to the brake disc 1, but the number of such arrangements may be higher for specific purposes. Further, in the embodiments according to Figs 4 and 5 the transmission by means of the bevel gear 17 and the bevel gear disc 19 may be replaced by a worm gear mechanism or any other type of angle transmission.

CLAIMS

1. An electronically controlled disc brake with self-servo effect, comprising:

a ramp plate (2) provided with a brake pad (3) for
5 engagement with a brake disc (1),
an actuator (14) for applying a control force on the
ramp plate substantially transverse to the brake disc,
a ramp bridge (4), and
rollers (6) movable in ramps (2', 4') in surfaces
10 facing each other of the ramp plate (2) and the ramp bridge
(4),

the arrangement being such that a movement of the
ramp plate (2) in the tangential direction of the brake
disc (1) will cause it to move towards or away from the
15 brake disc.

2. A disc brake according to claim 1, wherein there
are at least two ramp and roller arrangements (2', 4', 6)
between the ramp plate (2) and the ramp bridge (4).

3. A disc brake according to claims 1 and 2, wherein
20 the ramp bridge (4) is attached to a brake caliper (7)
placed astraddle of the brake disc (1).

4. A disc brake according to any of the preceding
claims, wherein the ramps (2', 4') are straight.

5. A disc brake according to any of claims 1-3,
25 wherein the ramps (2', 4') are curved.

6. A disc brake according to claim 2, wherein a
common roller cage is provided for the rollers (6).

7. A disc brake according to claim 1, wherein the
actuator is an electric motor (14).

30 8. A disc brake according to claim 1, wherein the
control force is applied by means of a control rod (9).

9. A disc brake according to claim 7, wherein the
control force is applied over an eccenter mechanism (19,
20; 19, 27, 28) between the ramp plate (2) and the ramp
35 bridge (4), the eccentricity of the mechanism and thus the

distance between the ramp plate and the ramp bridge being adjustable by means of the electric motor (14).

10. A disc brake according to claim 9, wherein there is provided in the force transmission from the electric
5 motor (14) a brake means (14') for keeping the outgoing shaft of the motor non-rotatable, when the motor is not energized for rotation in either of its two rotational directions.

11. A disc brake according to claim 9, wherein the
10 rotation of the electric motor (14) is transferred to the eccenter mechanism (19, 20; 19, 27, 28) via an angle transmission (17, 19) from a motor rod (15) to a bevel gear disc (19), which is rotatably attached to the ramp bridge (4) and is part of the eccenter mechanism.

15 12. A disc brake according to claim 11, wherein the rotation of the electric motor (14) is transferred to the eccenter mechanism (19, 20; 19, 27, 28) via a bevel gear (17) on the motor rod (15) in engagement with the bevel gear disc (19).

20 13. A disc brake according to claim 11, wherein the rotation of the electric motor (14) is transferred to the eccenter mechanism (19, 20; 19, 27, 28) via a worm gear mechanism.

25 14. A disc brake according to claim 12, wherein the bevel gear (17) is axially movable on the motor rod (15) by being in splines engagement therewith.

15. A disc brake according to claim 9, wherein the position of the ramp bridge (4) in relation to the brake caliper (7) may be adjusted in the direction transverse to
30 the brake disc (1) by means of two adjustment screws (11).

16. A disc brake according to claim 15, wherein the two adjustment screws (11) are connected by means of a chain (21) or the like for their synchronous rotation.

17. A disc brake according to claim 9, wherein a
35 force sensing means (22-25) for transmitting a signal

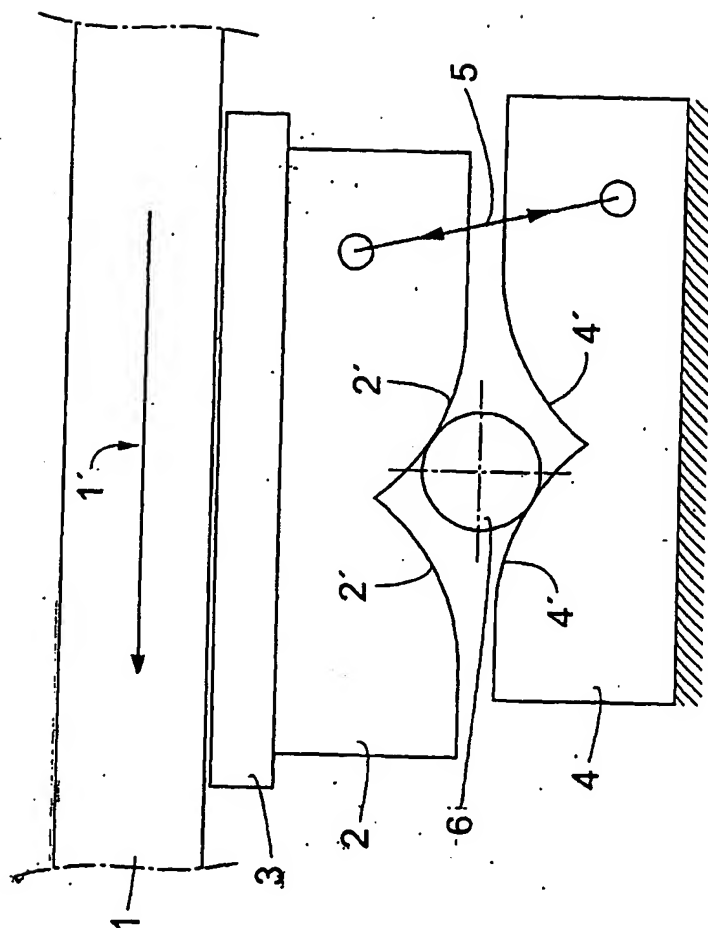
indicative of the tangential force is arranged between the ramp bridge (4) and the brake caliper (7).

18. A disc brake according to claim 17, wherein a force sensing means (22-25) is arranged at either side of
5 the ramp bridge (4).

19. A disc brake according to claims 9 and 15, wherein a force sensing means for transmitting a signal indicative of the axial force is arranged between the adjustment screw (11) and the brake caliper (7).

10 20. A disc brake according to claim 9, wherein a crank rod (20) is pivotably attached at one of its ends to the ramp plate (2) and at its other end eccentrically to the bevel gear disc (19).

15 21. A disc brake according to claim 9, wherein a roller (27) is eccentrically rotatably attached to the bevel gear (19) and is in engagement with a slot (28) in the ramp plate (2) substantially parallel with the brake disc (1).



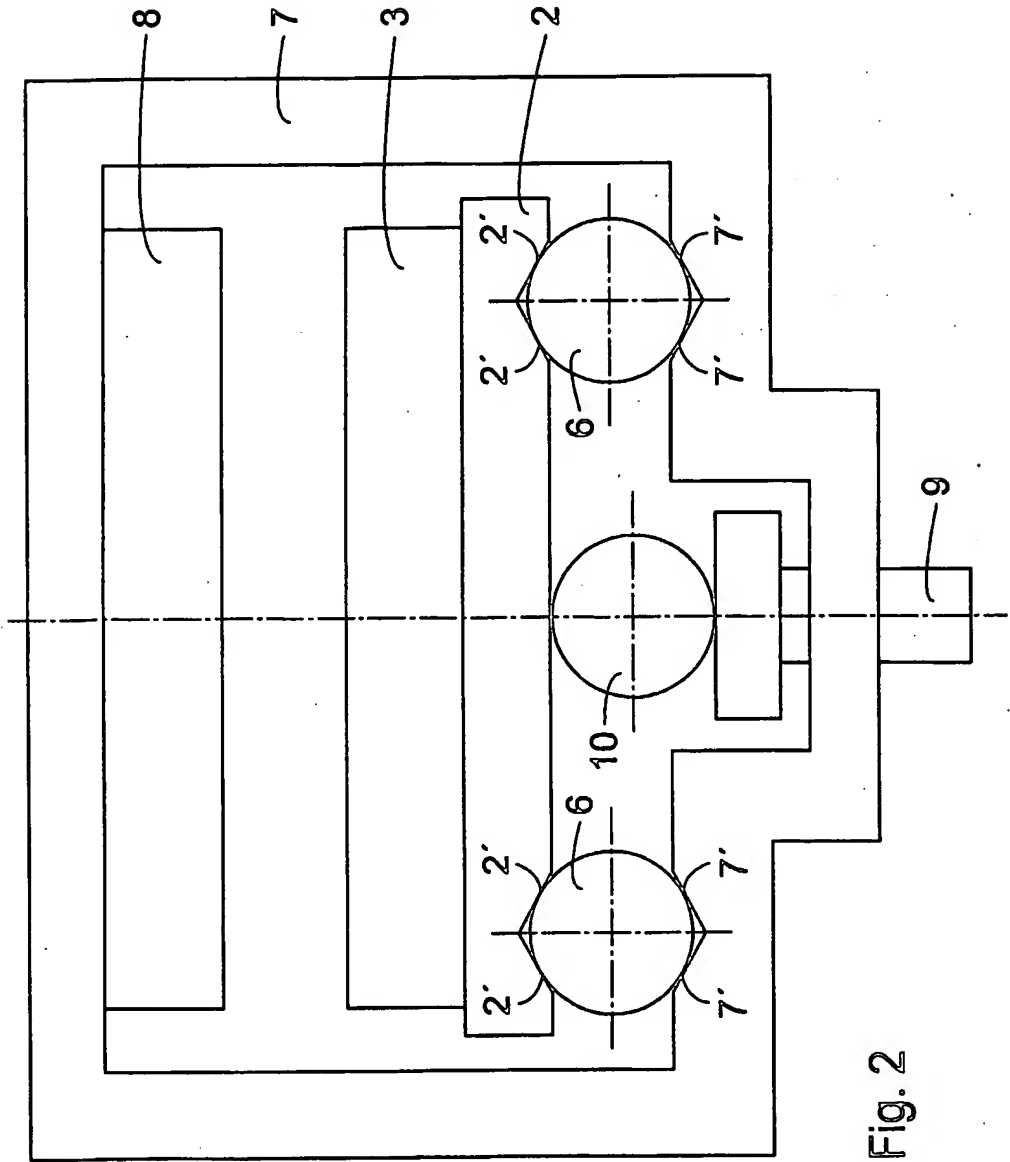


Fig. 2

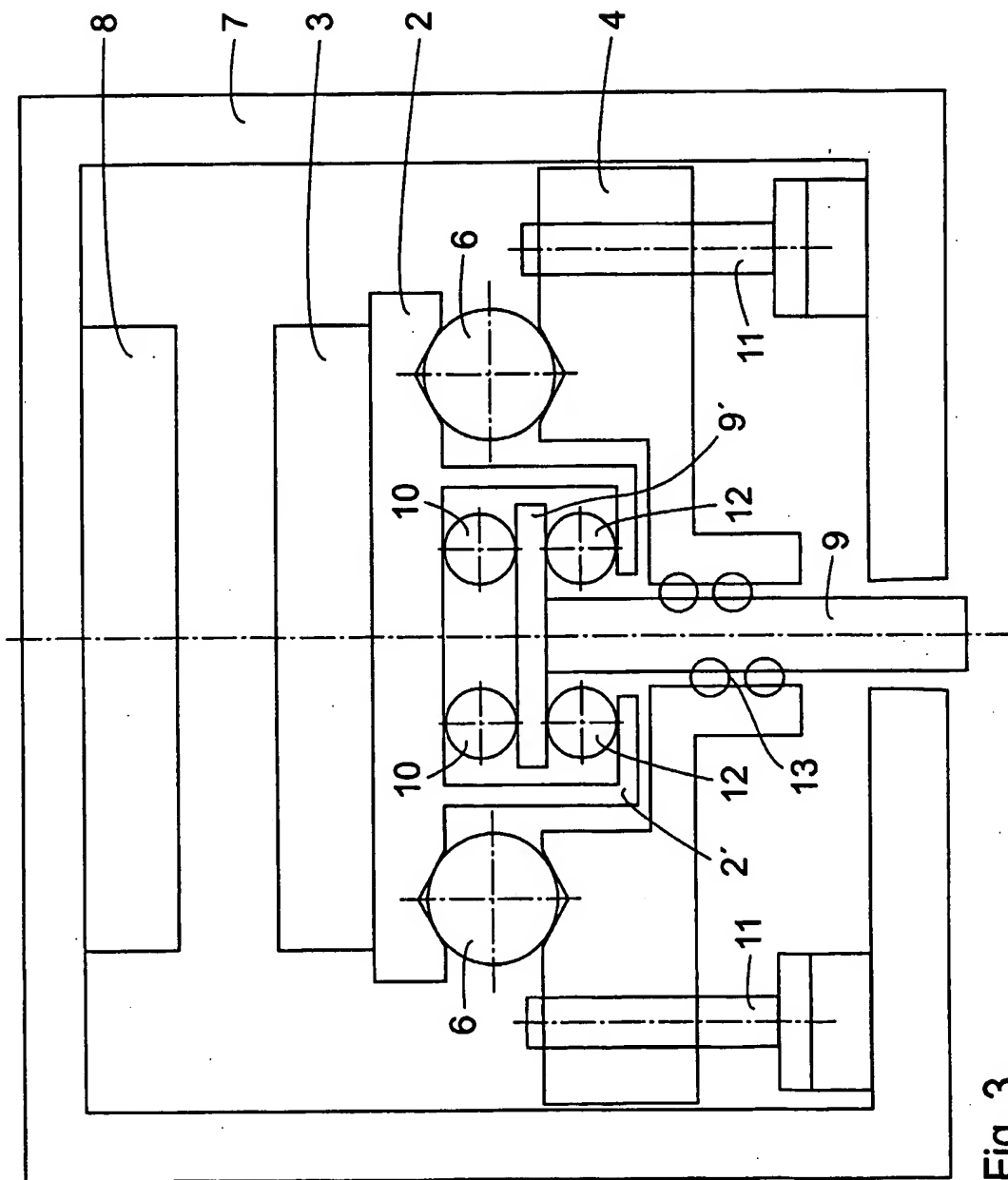
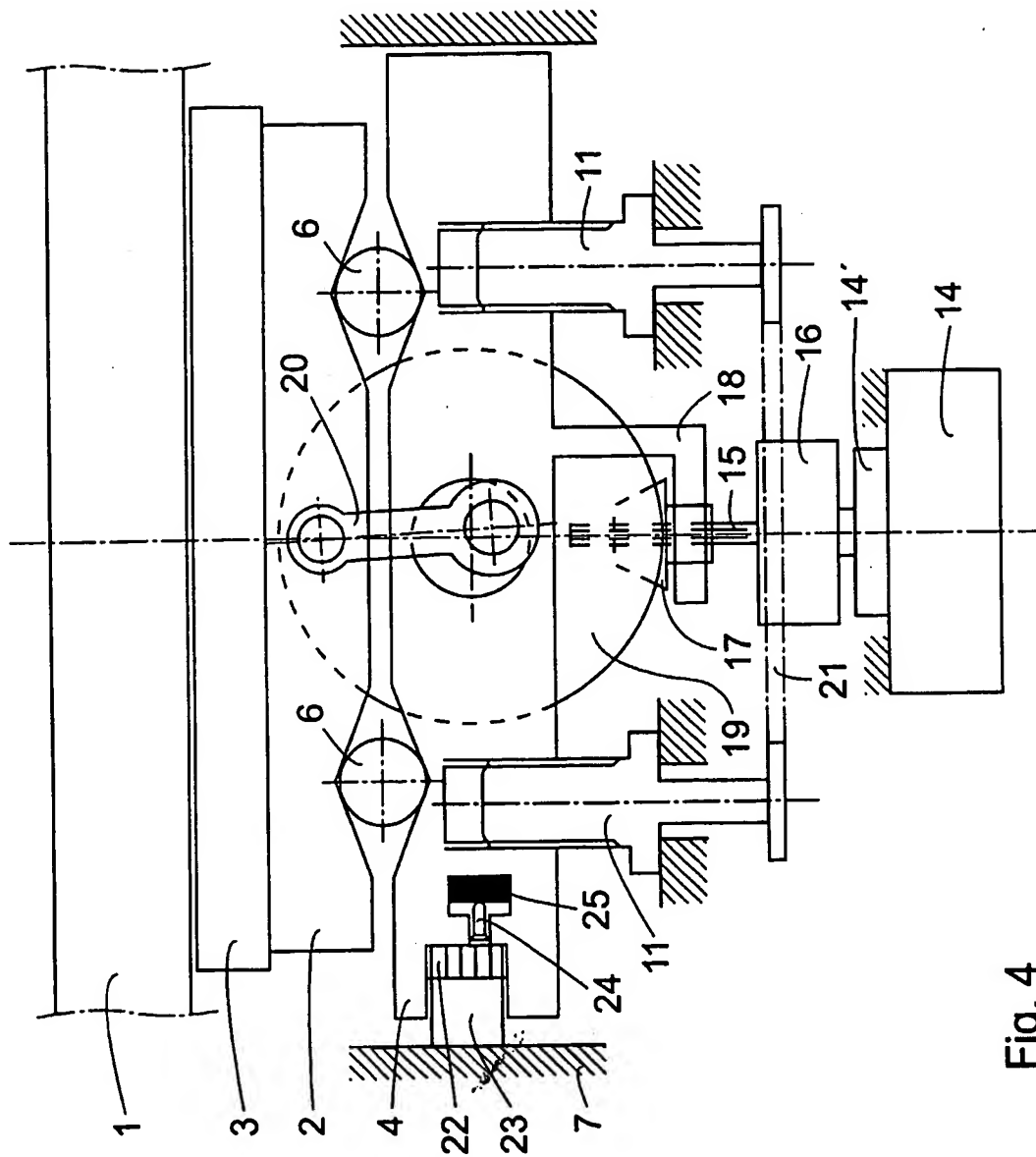


Fig. 3



5/6

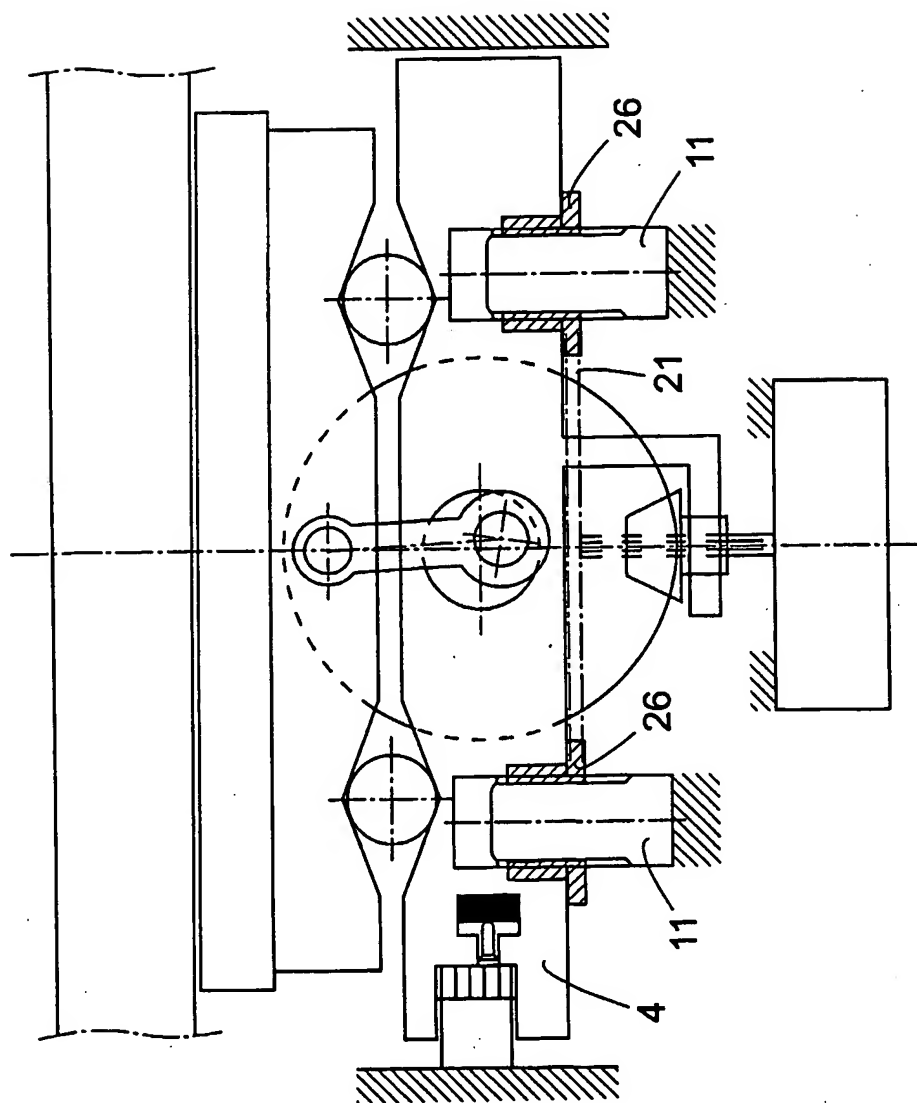


Fig. 5

6/6

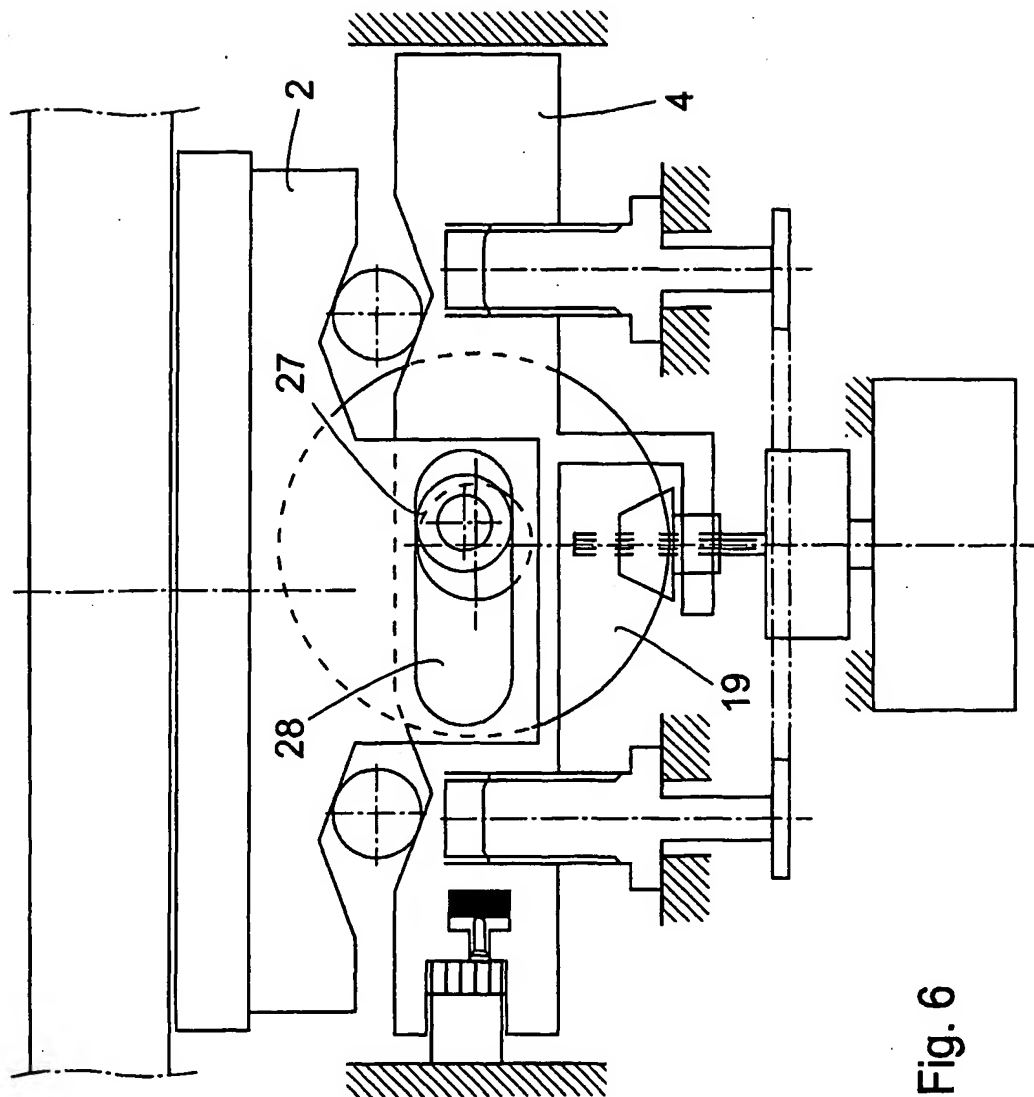


Fig. 6

INTERNATIONAL SEARCH REPORT

International application No.

PCT/SE 03/00290

A. CLASSIFICATION OF SUBJECT MATTER

IPC7: F16D 55/22, B60T 13/72

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)

IPC7: F16D, B60T

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

SE,DK,FI,NO classes as above

Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)

EPO-INTERNAL, WPI DATA, PAJ

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
Y	US 3651897 A (HAHN), 28 March 1972 (28.03.72), column 3, line 51 - column 4, line 63, figures 3,4, abstract --	1-8
Y	US 5915504 A (DÖRICH), 29 June 1999 (29.06.99), column 7, line 4 - line 45, figures 4,7, abstract --	1-8
A	US 5529150 A (BUCKLEY ET AL), 25 June 1996 (25.06.96), figures 2,3,11, claim 1, abstract --	1-8

☒ Further documents are listed in the continuation of Box C.

☒ See patent family annex.

* Special categories of cited documents:

"A" document defining the general state of the art which is not considered to be of particular relevance

"E" earlier application or patent but published on or after the international filing date

"L" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified)

"O" document referring to an oral disclosure, use, exhibition or other means

"P" document published prior to the international filing date but later than the priority date claimed

"T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention

"X" document of particular relevance: the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone

"Y" document of particular relevance: the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art

"&" document member of the same patent family

Date of the actual completion of the international search

15 May 2003

Date of mailing of the international search report

16 -05- 2003

Name and mailing address of the ISA/

Swedish Patent Office

Box 5055, S-102 42 STOCKHOLM

Facsimile No. +46 8 666 02 86

Authorized officer

Alexandra Jarlmark/EK

Telephone No. +46 8 782 25 00

INTERNATIONAL SEARCH REPORT

International application No.

PCT/SE 03/00290

C (Continuation). DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
A	US 4022299 A (HARAIKAWA), 10 May 1977 (10.05.77), column 2, line 19 - line 64, figures 1,2, abstract --	1-8
A	US 4228875 A (HARAIKAWA ET AL), 21 October 1980 (21.10.80), figure 1, claim 1, abstract -- -----	1-8

INTERNATIONAL SEARCH REPORT
Information on patent family members

29/04/03

International application No.
PCT/SE 03/00290

Patent document cited in search report	Publication date	Patent family member(s)	Publication date
US 3651897 A	28/03/72	CA 920069 A GB 1343325 A	30/01/73 10/01/74
US 5915504 A	29/06/99	DE 19629936 C FR 2753672 A,B GB 2315527 A,B GB 9715703 D	20/11/97 27/03/98 04/02/98 00/00/00
US 5529150 A	25/06/96	GB 2300889 A,B GB 2333336 A,B GB 9605773 D GB 9908284 D US 5647459 A	20/11/96 21/07/99 00/00/00 00/00/00 15/07/97
US 4022299 A	10/05/77	CA 1052298 A CA 1058532 A DE 2606303 A,B,C DE 2659848 A,B,C FR 2300937 A,B GB 1537507 A IT 1057209 B JP 1154771 C JP 51094066 A JP 57049775 B JP 1185224 C JP 51094067 A JP 58003132 B	10/04/79 17/07/79 26/08/76 25/08/77 10/09/76 29/12/78 10/03/82 15/07/83 18/08/76 23/10/82 20/01/84 18/08/76 20/01/83
US 4228875 A	21/10/80	JP 1267778 C JP 53079033 A JP 59043443 B	10/06/85 13/07/78 22/10/84